Homework till Monday

Modeling in Knowledge Representation: The Parthood Relation

Stefano Borgo LOA, ISTC, CNR Carola Eschenbach Hamburg University Laure Vieu IRIT, CNRS & LOA, ISTC, CNR Doctorate Course 2006-2007

- How do your research interest relate to the topics of the course ?
- In which way do parts / the notion of 'part' play a role in your area ?
- Which kinds of parts / wholes play a role ?
- Is the spatial structure important (e.g. spatial connectedness) ?
- Where do temporal notions come up?
- Are temporal instants sufficient for your needs? Where can time periods be important ?

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2

3-Mereotopology

Doctorate Course Modeling in Knowledge Representation: The Parthood Relation 2006-2007

Why topological notions?

Mereology alone

- does not have any notion of 'whole', 'integrity', 'connectedness'
- does not distinguish spatially coherent (one-piece) entities from spatially disconnected (multi-piece) entities
- does not distinguish inner parts from boundary parts



Mathematical Contribution

Point-set Topology

- establishment at the beginning of the 20th century
- general theory for describing continuity
- continuity: predictability of the behavior of a function at the boundary from the behavior in the interior of a set
- Points are undefined primitive objects that serve as basis (carrier) for the structure
- Sets of points define and exhibit the topological structure



5

7

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Why Mereotopology ?

Formalizing common-sense knowledge

- proved to be much harder than formalized expert knowledge
- is based on a common-sense ontology
- that includes objects of every day live
- rather than sets.

Mathematics (Topology)

- uses set theory to represent real world problems
- provides sophisticated tools for expert reasoning.

Relations between Points and Sets

Set Theory

Points are element of the set
or not.

Topology

Points are interior to the set (then they are elements of the set)
exterior to the set (then they are not elements of the set)
or boundary points of the set

boundary points can be elements of the set
or not.

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Topology: A Reminder

Definition

- A topology on a carrier set D is (given by) a set T⊆ 2^D having the following properties
 - D, $\emptyset \in \mathcal{T}$
 - $\forall S \subseteq \mathcal{T}[\bigcup S \in \mathcal{T}]$
 - $\forall X, Y \in \mathcal{T}[X \cap Y \in \mathcal{T}]$
- The elements of \mathcal{T} are called open sets.

Simple Examples

- {D, Ø} (trivial topology)
- 2^D (discrete topology)

Topology Based on a Metric Space

- Let $\langle D, d \rangle$ be a metric space, (d: $D \times D \rightarrow \mathbb{R}$).
- The open ball (in D) of diameter $0 < \epsilon \in \mathbb{R}$ around x is defined as:
 - $\mathsf{B}_{\mathsf{d}}(\mathsf{x},\,\varepsilon) = \{\mathsf{y} \in \mathsf{D} \mid \mathsf{d}(\mathsf{x},\,\mathsf{y}) < \varepsilon\}$
- Let \mathcal{B}_d be the set of all open balls around any point of D, i.e. $\mathcal{B}_d = \{B_d(x, \epsilon) \mid 0 < \epsilon \in \mathbb{R}, x \in D\}$
- Then the set $\mathcal{T}_d = \{\bigcup M \mid M \subseteq \mathcal{B}_d\}$ is a topology for D.

Examples

- D = \mathbb{R} ; open balls are open intervals
- D = \mathbb{R}^2 ; open balls are discs without bounding circle line
- D = \mathbb{R}^3 ; open balls are spheres without surface

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Topology Induced by a Metric

- Example: Let $\langle D, d \rangle$ be a metric space.
- Let $\mathcal{T}_{d} = \{\bigcup M \mid M \subseteq \mathcal{B}_{d}\}.$
- Show
 - D, $\emptyset \in \mathcal{T}_d$
 - ${}^{\bullet} \, \forall S \subseteq \mathcal{T}_d \; [\bigcup S \in \mathcal{T}_d]$
 - $\forall X, Y \in \mathcal{T}_d \ [X \cap Y \in \mathcal{T}_d]$
- Show and take advantage of: $\forall B \in \mathcal{B}_d [B = \bigcup \{X \in \mathcal{B}_d \mid X \subseteq B\}]$

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10

Points in Topology



Functions Mapping Sets in Topology



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General Laws for the Mappings Defined





Open and Closed Sets

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14



Regular Sets

Let \mathcal{T} be a topology on D and M \subseteq D.

(drop index $_{\mathcal{T}}$ for simplicity)

- M is regular iff cl(int(M)) = cl(M) and int(cl(M)) = int(M).
- M is an open regular set iff OP(M) and int(cl(M)) = int(M).
- M is a closed regular set iff CL(M) and cl(int(M)) = cl(M).
- Unions and intersections of regular sets need not be regular!
- Use (topology-specific) regular union / intersection.



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Basic Concepts of Point-Set Topology

Equivalent axiomatizations based on different primitives

- Open Set
 - a set without a boundary
- Closure
 - mapping a set to the set of all its limit points
- Neighborhoods of a point
 - a neighborhood of a point is extended around the point in all 'directions'

Spatial Structure: Mereotopological Calculi

Basic idea

- (extended) regions are basic entities in the spatial ontology
- topological structure is crucial for spatial structure (→ qualitative)
- points and boundaries are abstractions from configurations of regions



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17

Topology and Mereology

Beginning of Topology

- Fréchet (1906): Spatial structure of the space of functions
- Hausdorff (1914): General conditions for convergence; Definition of Topology based on 'Neighborhood'
- Kuratowski (1922): Topology based on 'Closure'

Mereology

- Lesniewski (1927–30): Development of Mereology as alternative to set-theory
- Leonard & Goodman (1940): Mereology as a 'Calculus of Individuals'
- Simons (1987): Discussion of alternative axiomatic systems

Mereotopology (1)

- de Laguna (1922): Points and boundaries as abstractions from extended regions
- Whitehead (1929): Proposal of a region-based description of space
- Clarke (1981): Calculus of Individuals based on 'Connection'
- Allen (1981): Time periods in Al
- Randell, Cohn (1989); Vieu (1993): Adaptation of Clarke's calculus for Al
- Egenhofer (1991): Relations between regions based on point-set topology for GIS

Mereotopology (2)

- Randell, Cui, Cohn (1992): Alternative calculus by 'redefining complement'
- Smith (1993): Mereotopology based on 'inner parts'
- Asher & Vieu (1995): geometry of common sense
- Eschenbach & Heydrich (1995): Regions embedded in extensional Mereology
- Varzi (1996): Discussion of alternative axiomatic systems
- Borgo, Guarino, Masolo (1996): pointless theory of space
- Roeper (1997): Region-based Topology
- Masolo & Vieu (1999): Atoms in Mereotopology
- Eschenbach (1999): Closed Region Calculus
- ... still an open discussion

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21

Mereotopologies

- A large selection of proposals exist
- Whitehead (1929), Clarke (1981), Randell & Cohn (1989), Egenhofer (1991), Randell Cui & Cohn (RCC, 1992), Vieu (1993), Asher & Vieu (A&V, 1995), Roeper (1997), Eschenbach (CRC, 1999), Borgo, Guarino, Masolo (BGM, 1996)
- Is there a common core to the proposals?
- Which approaches can be combined?
- How to choose between 'the proposals' for an application?

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22

How to proceed?

Select terminologies

- Use notation that is neutral regarding the theories
- · Identify the common terminological kernel
- Distinguish terms whose definitions differ
 - Mereological terminology (def. based on Part-of <)
 - Topological terminology (def. based on contact C)
 - Mereotopological terminology (def. based on < and C)

Identify a list of axioms

• such that every approach can be identified with a subset Analyse the interrelation between the axioms

Select Terminologies

Problems / Obstacles



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Mereological Terminology (M): Mereology: Formalization of the relation of *part* (<)



Defining Functions: Complements



- (D) $x = compl(y) \Leftrightarrow_{def} \forall u [C(u, x) \Leftrightarrow \exists w [C(u, w) \land \neg C(w, y)]]$
- (D) $x = compl(y) \Leftrightarrow_{def} \forall u [C(u, x) \Leftrightarrow \neg (u <<_i y)] \land \forall u [u \circ x \Leftrightarrow \neg (u < y)]$
- In order to define a function in standard logic
- the definiens should guarantee (within the assumed theory)
 - uniqueness
 - existence
- To allow comparison,
- use unique names
- replace n-ary function-symbol by (n+1)-ary relational symbol x = name_f(y) ⇔_{def} Ψ(x, y) id-name_f(x; y) ⇔_{def} Ψ(x, y)

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26

Binary Topological Relations



25

Binary Topological Relations



Binary Topological Relations



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Binary Topological Relations



Mereological and Topological Terminology



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30

Mereotopological Terminology (M+T): Relating Mereology and Topology

Minimal condition

- Parts are (topologically) enclosed
- (A) $\forall x \ y \ [x \le y \Rightarrow \mathsf{E}(x, y)]$
- Overlapping regions are (topologically) superposed and, thus, connected

More specific assumptions

 Replacing Mereology: Identifying the relations part and enclosure

Mereotopological Notions: Refinement of Mereological Relations

- External connection (EC): Connection without overlap
- *tangential part* (<_t), *internal part* (<_i)

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33

Mereological and Topological Terminology



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34

Mereological and Topological Terminology



(Selection of) Binary Relations in Mereotopology



Identify a List of Axioms

Study interactions

The axioms used up to now are

- $M: \qquad \forall x \ y \ z \ [z < x \land x < y \Longrightarrow z < y]$
- **M**: $\forall x \ y \ [x < y \land y < x \Rightarrow x = y]$
- **M**: $\forall x [x < x]$
- **T**: $\forall x [C(x, x)]$
- **T**: $\forall x \ y \ [C(x, y) \Longrightarrow C(y, x)]$
- **M+T**: $\forall x \ y \ [x < y \Rightarrow E(x, y)]$

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38

Types of Axioms

- Principles of extensionality, supplementation (individuation)
- Interaction between mereological and topological terminology
- Topological and mereological universes
- Existence of open and / or closed regions; divisibility
- A first map
- Atoms and connectedness of space
- Three types of complements and connectedness
- (Further axioms for connectedness)

Extensionality and Interaction of Mereological and Topological Terms

Extensionality

 $\begin{array}{l} \label{eq:principles of Extensionality} \\ \Psi \text{ is a formula in which x and z occur freely (but y does not)} \\ \forall x \ y \ [x \ \neq \ y \Rightarrow \exists z \ [\Psi \Leftrightarrow \neg \Psi[x/y]]] \\ \forall x \ y \ [\forall z \ [\Psi \Leftrightarrow \Psi[x/y]] \Rightarrow x = y] \end{array} \\ \\ \mbox{For example, the principle of extensionality in set} \\ theory: \\ \forall s1 \ s2 \ [s1 \ \neq \ s2 \Rightarrow \exists a \ [a \ \in \ s1 \Leftrightarrow \neg(a \ \in \ s2)]] \\ \forall s1 \ s2 \ [\forall a \ [a \ \in \ s1 \Leftrightarrow a \ \in \ s2] \Rightarrow s1 = s2] \end{array} \\ \\ \mbox{Supplementation in the context of Mereology} \\ (employing antisymmetry \ of \ <) \\ \forall x \ y \ [\neg(x < y) \Rightarrow \exists z \ [\Psi \land \neg \Psi[x/y]]] \\ \forall x \ y \ [\forall z \ [\Psi \Rightarrow \Psi[x/y]] \Rightarrow x < y] \end{array}$

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41

Extensionality and the interaction between mereology and topology

ET: Extensional Topology



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42



Space of Theories (Extensionality)

Space of Theories (Extensionality)



Terminological Simplifications in EM+WT



Space of Theories (Extensionality)



Why not M+ST?

M+ST: $\forall x \ y \ [E(x, y) \Rightarrow x < y]$

Assuming the cells not to have proper parts:

The black square is enclosed

by the gray area without being

(First Part of) A first map



its part.



Principles of extensionality do not contradict each other

Mereologically and Topologically Universal Regions

Universal Regions

 $\begin{array}{l} \mbox{Mereologically universal regions} \\ \mbox{m-univ}(x) \Leftrightarrow_{def} \forall y [y \circ x] \\ \mbox{M} = \forall x [m-univ(x) \Leftrightarrow \forall y [y < * x]] \\ \mbox{M} = \forall x [W [y < x] \Rightarrow m-univ(x)] \\ \mbox{EM} = \forall x [W [y < x] \Rightarrow m-univ(x)] \\ \mbox{EM} = \forall x [m-univ(x) \Leftrightarrow \forall y [y < x]] \\ \mbox{UM}: There is a mereologically universal region \\ \mbox{f} x [m-univ(x)] \\ \mbox{Topologically universal regions} \\ \mbox{t-univ}(x) \Leftrightarrow_{def} \forall y [C(y, x)] \\ \mbox{T} |= \forall x [t-univ(x) \Leftrightarrow \forall y [E(y, x)]] \\ \mbox{T} |= \forall x [t-univ(x) \Leftrightarrow \forall y [S(y, x)]] \\ \mbox{UT}: There is a topologically universal region \\ \mbox{f} x [t-univ(x)] \end{array}$

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Universal Regions (2)

Different versions for Mereology and Topology m-univ(x) $\Leftrightarrow_{def} \forall y [y \circ x]$ t-univ(x) $\Leftrightarrow_{def} \forall y [C(y, x)]$

 $\mathbf{M+T} \models \forall x \ [\text{m-univ}(x) \Rightarrow \text{t-univ}(x)]$

M+OT: Topologically universal regions are

- mereologically universal
- $\forall x [t-univ(x) \Rightarrow m-univ(x)]$
- The grey area is topologically universal but not mereologically universal.



51



Space of Theories (Universal Regions)





Space of Theories (Universal Regions)



(Second Part of) A first map



Closed and Open Regions

Closed and Open Regions

Point-Set Topology

• Closed sets include all their boundaries.

• Missing connections of closed regions derive from missing parts.



59

 $CL(x) \Leftrightarrow_{def} \forall y [y \le x \Rightarrow E(y, x)]$

 $\mathbf{M} + \mathbf{T} \models \forall x \left[\mathsf{CL}(x) \Leftrightarrow \forall y \left[\exists z \left[\mathsf{C}(z, y) \land \neg \mathsf{C}(z, x) \right] \Rightarrow \exists w \left[w < y \land \neg (w \bigcirc x) \right] \right] \right]$

• Open sets do not include their boundaries.

- All connections derive from sharing parts.
- There are no external connections to open regions.

 $OP(x) \Leftrightarrow_{def} \neg \exists y [EC(y, x)]$



Closed Regions and Closures

A region is *closed* iff it encloses all regions it covers. $CL(x) \Leftrightarrow_{def} \forall y [y < x \Rightarrow E(y, x)]$ **M+T_{CL}:** All regions are closed $\forall x [CL(x)]$ A *closure* of region *y* is connected to exactly those regions that are connected to a region *y* covers. $cl(x; z) \Leftrightarrow_{def} \forall u [C(u, x) \Leftrightarrow \exists y [y < z \land C(u, y)]]$ **M+T** $\models \forall x y [cl(x; z) \Rightarrow \forall y [y < z \Rightarrow E(y, x)]$ **M+T** $\models \forall x [CL(x) \Leftrightarrow cl(x; x)]$ **M+KT:** All regions have a closure $\forall y \exists x [cl(x; y)]$



Theories with Closed Regions and Closures

Theories with Closed Regions and Closures



Theories with Closed Regions and Closures



Theories with Closed Regions and Closures





(Third Part of) A first map

Principles of extensionality do not contradict each other Mereological extensionality stronger than closedness of regions

